Modulating, Spring Return, AC 24 V/DC, for DC 2... 10 V or $4 . . .20 \mathrm{~mA}$ Control Signal



| Electrical data | Nominal voltage | AC/DC 24 V |
| :---: | :---: | :---: |
|  | Nominal voltage frequency | $50 / 60 \mathrm{~Hz}$ |
|  | Power consumption in operation | 5.5 W |
|  | Power consumption in rest position | 3 W |
|  | Transformer sizing | 8.5 VA (class 2 power source) |
|  | Auxiliary switch | $2 \times$ SPDT, 3 A resistive ( 0.5 A inductive) @ AC 250 V, one set at $10^{\circ}$, one adjustable 10 ... $90^{\circ}$ |
|  | Switching capacity auxiliary switch | 3 A resistive (0.5 A inductive) @ AC 250 V |
|  | Electrical Connection | (2) 18 GA appliance cables with $1 / 2^{\prime \prime}$ conduit connectors, $3 \mathrm{ft}[1 \mathrm{~m}]$, |
|  | Overload Protection | electronic throughout 0...95 ${ }^{\circ}$ rotation |
|  | Electrical Protection | actuators are double insulated |
| Functional data | Torque motor | $180 \mathrm{in-lb}$ [20 Nm] |
|  | Operating range $Y$ | $2 . . .10 \mathrm{~V}$ |
|  | Operating range Y note | $4 . . .20 \mathrm{~mA} \mathrm{w/} \mathrm{ZG-R01} \mathrm{( } 500 \Omega, 1 / 4 \mathrm{~W}$ resistor) |
|  | Input Impedance | $100 \mathrm{k} \Omega$ for $2 . . .10 \mathrm{~V}(0.1 \mathrm{~mA}), 500 \Omega$ for $4 \ldots . .20 \mathrm{~mA}$ |
|  | Position feedback U | 2...10 V |
|  | Position Feedback | 2... 10 V , Max. 0.5 mA |
|  | Position feedback U note | Max. 0.5 mA |
|  | Direction of motion motor | selectable with switch 0/1 |
|  | Direction of motion fail-safe | reversible with $\mathrm{cw} / \mathrm{ccw}$ mounting |
|  | Manual override | 5 mm hex crank (3/16" Allen), supplied |
|  | Angle of rotation | $95^{\circ}$, adjustable with mechanical end stop, $35 . . .95^{\circ}$ |
|  | Angle of rotation note | adjustable with mechanical end stop, 35...95 |
|  | Running Time (Motor) | 95 s |
|  | Running time fail-safe | $<20 \mathrm{~s} @-4 . . .122^{\circ} \mathrm{F}\left[-20 . . .50^{\circ} \mathrm{C}\right]$, <60 s @ - $22^{\circ} \mathrm{F}$ [-30$\left.{ }^{\circ} \mathrm{C}\right]$ |
|  | Running time fail-safe note | @ -4...122 ${ }^{\circ} \mathrm{F}\left[-20 . . .50^{\circ} \mathrm{C}\right.$, $<60 \mathrm{~s} @-22^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right]$ |
|  | Noise level, motor | 40 dB (A) |
|  | Noise level, fail-safe | 62 dB (A) |
|  | Shaft Diameter | $1 / 2 . . .1 .05$ " round, centers on $1 / 2^{\prime \prime}$ and $3 / 4^{\prime \prime}$ with insert, 1.05 " without insert |
|  | Position indication | Mechanical |
| Safety data | Degree of protection IEC/EN | IP54 |
|  | Degree of protection NEMA/UL | NEMA 2 |
|  | Enclosure | UL Enclosure Type 2 |
|  | Agency Listing | cULus listed to UL60730-1A:02; UL 60730-2-14:02 and CAN/CSA-E60730-1:02; Listed to UL 2043 suitable for use in air plenums per Section 300.22(c) of the NEC and Section 602.2 of the IMC |
|  | Quality Standard | ISO 9001 |


|  | Ambient temperature | $-22 \ldots 122^{\circ} \mathrm{F}\left[-30 \ldots . .50^{\circ} \mathrm{C}\right]$ |
| :--- | :--- | :--- |
|  | Storage temperature | $-40 \ldots 176^{\circ} \mathrm{F}\left[-40 \ldots 80^{\circ} \mathrm{C}\right]$ |
| Ambient humidity | max. $95 \%$ r.H., non-condensing |  |
| Servicing | Waintenance-free |  |
|  | Weight | $4.2 \mathrm{lb}[1.9 \mathrm{~kg}]$ |
| Housing material | Galvanized steel and plastic housing |  |

## Product features

Application For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05 " in diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The actuator operates in response to a DC 2... 10 Vor, with the addition of a $500 \Omega$ resistor, a $4 . . .20 \mathrm{~mA}$ control input from an electronic controller or positioner. A DC $2 . . .10 \mathrm{~V}$ feedback signal is provided for position indication.

A common installation technique for control of multi-section dampers is to use the U5 position feedback of one actuator (Master) to control multiple actuators (Slaves). Belimo refers to this as Master/Slave control. The only requirement is that the actuators are installed on MECHANICALLY SEPARATE damper shafts.

Operation The AF..24-SR-S series actuators provide true spring return operation for reliable fail-safe application and positive close off on air tight dampers. The spring return system provides constant torque to the damper with, and without, power applied to the actuator. The AF.. $24-S R-S$ series provides $95^{\circ}$ of rotation and is provided with a graduated position indicator showing $0^{\circ}$ to $95^{\circ}$. The AF.. $24-S R-S$ uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The AF..24-SR-S versions are provided with two built-in auxiliary switches. These SPDT switches provide safety interfacing or signaling, for example, for fan start-up. The switching function at the fail-safe position is fixed at $10^{\circ}$, the other switch function is adjustable between $10^{\circ}$ to $90^{\circ}$. The AF..SR-S actuator is shipped at $5^{\circ}$ ( $5^{\circ}$ from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.
ATTENTION: AF..24-SR-S cannot be tandem mounted on the same damper or valve shaft. Only On/Off and MFT AF.. models can be used for tandem mount applications.

Typical specification Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a $1.05^{\prime \prime}$ diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Accessories

| Electrical accessories | Description | Type |
| :--- | :--- | :--- |
|  | Auxiliary switch, mercury-free | IRM-100 |
|  | Auxiliary switch, mercury-free | P475 |
|  | Signal Siumlator, Power supply AC 230 V | P475-1 |
|  |  | PS-100 |
|  | Positioner for wall mounting | PTA-250 |
|  | Positioner for front-panel mounting | SGA24 |
|  | Cable Conduit Connector $1 / 2^{\prime \prime}$ | SGF24 |
|  | Resistor, $500 \Omega, 1 / 4$ " wire resistor with $6 "$ pigtail wires | TF-CC US |
|  | ZG-R01 |  |



Electrical installation

## Warning! Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

$\uparrow$
Meets cULus requirements without the need of an electrical ground connection.

$\Delta$
Apply only AC line voltage or only UL-Class 2 voltage to the terminals of auxiliary switches. Mixed or combined operation of line voltage/safety extra low voltage is not allowed.
(A) Actuators with appliance cables are numbered.

1 Provide overload protection and disconnect as required.
3 Actuators may also be powered by 24 VDC.
4 Two built-in auxiliary switches (2x SPDT), for end position indication, interlock control, fan startup, etc.

5 Only connect common to negative (-) leg of control circuits.
7 A $500 \Omega$ resistor ( $\mathrm{ZG}-\mathrm{RO} 1$ ) converts the $4 . . .20 \mathrm{~mA}$ control signal to $2 . . .10 \mathrm{~V}$.
11 Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.

2... $10 \mathrm{~V} / 4 . . .20 \mathrm{~mA}$ Control

- $\triangle \triangle$ -


Auxiliary Switches

## Dimensions

Dimensional drawings


